

November 17th, 2015





9:00am $f(x) = \sum_{S \subseteq [n]} \widehat{f}(S) \chi_S(x)$





















And now

Prepare 15-251 slides



Markov Model

Markov Model

Andrey Markov (1856 - 1922)

Russian mathematician.

Famous for his work on <u>random processes</u>.



 $(\Pr[X \ge c \cdot \mathbf{E}[X]] \le 1/c$ is Markov's Inequality.)

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A model for the evolution of a random system. The future is independent of the past, given the present.

Cool things about the Markov model

- It is a very general and natural model.
 - Extraordinary number of applications in many different disciplines:
 - computer science, mathematics, biology, physics, chemistry, economics, psychology, music, baseball,...

- The model is simple and neat.

- A beautiful mathematical theory behind it. Starts simple, goes deep.

The plan

Motivating examples and applications

Basic mathematical representation and properties



The future is independent of the past, given the present.

Some Examples of Markov Models

Example: Drunkard Walk



Example: Diffusion Process



Example: Weather

A very(!!) simplified model for the weather. S = sunnyProbabilities on a daily basis: R = rainyPr[sunny to rainy] = 0.1S R Pr[sunny to sunny] = 0.9 $\begin{array}{c|c} S & 0.9 & 0.1 \\ R & 0.5 & 0.5 \end{array}$ Pr[rainy to rainy] = 0.5Pr[rainy to sunny] = 0.5 0.5 0.1 Rainy Sunny 0.5 Encode more information about current state for a more accurate model.

Example: Life Insurance

Goal of insurance company:

figure out how much to charge the clients.

Find a model for how long a client will live.

Probabilistic model of health on a monthly basis:

Pr[healthy to sick] = 0.3 Pr[sick to healthy] = 0.8 Pr[sick to death] = 0.1 Pr[healthy to death] = 0.01 Pr[healthy to healthy] = 0.69 Pr[sick to sick] = 0.1 Pr[death to death] = 1

Example: Life Insurance

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Some Applications of Markov Models

Application: Algorithmic Music Composition

Nicholas Vasallo

Megalithic Copier #2: Markov Chains (2011)

written in Pure Data

Application: Image Segmentation



Application: Automatic Text Generation

Random text generated by a computer (putting random words together):

"While at a conference a few weeks back, I spent an interesting evening with a grain of salt."

<u>Google</u>: Mark V Shaney

Application: Speech Recognition

Speech recognition software programs use Markov models to listen to the sound of your voice and convert it into text.

1997: Web search was horrible



Sorts webpages by number of occurrences of keyword(s).



Larry Page Sergey Brin

\$20Billionaires



Jon Kleinberg

Nevanlinna Prize

How does Google order the webpages displayed after a search?

<u>2 important factors:</u>

- Relevance of the page.
- Reputation of the page.
 The number and reputation of links pointing to that page.

Reputation is measured using PageRank.

PageRank is calculated using a Markov Chain.



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The Setting

There is a system with *n* possible states/values.

At each time step, the state changes probabilistically.


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Memoryless

The next state only depends on the current state.

Evolution of the system: random walk on the graph.

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The Definition

A Markov Chain is a directed graph with $V = \{1, 2, ..., n\}$ such that:

- Each edge is labeled with a value in (0, 1]self-loops allowed (a positive probability).
- At each vertex, the probabilities on outgoing edges sum to $1\,.$
- (-We usually assume the graph is strongly connected. i.e. there is a path from *i* to *j* for any *i* and *j*.)

The vertices of the graph are called states.

- The edges are called transitions.
- The label of an edge is a transition probability.

Example: Markov Chain for a Lecture



This is not strongly connected.

Given some Markov Chain with n states:

For each $t = 0, 1, 2, 3, \ldots$ we have a random variable: $X_t =$ the state we are in after t steps. 2 $\pi_t = [p_1 \ p_2 \ \cdots \ p_n]$ Define $\pi_t |i| = \Pr[X_t = i]$. $\sum p_i = 1$ $\pi_t[i] =$ probability of being in state *i* after **t** steps. We write $X_t \sim \pi_t$. (X_t has distribution π_t)

Note that someone has to provide π_0 .

Once this is known, we get the distributions π_1, π_2, \ldots

Let's say we start at state I, i.e., $X_0 \sim \begin{bmatrix} 1 & 2 & 3 & 4 \\ 0 & 0 & 0 \end{bmatrix} = \pi_0$



 $X_0 = 1 \qquad X_0 \sim \pi_0$

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 $X_0 = 1 \qquad X_0 \sim \pi_0$ $X_1 = 4 \qquad X_1 \sim \pi_1$

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- $X_0 = 1 \qquad X_0 \sim \pi_0$ $X_1 = 4 \qquad X_1 \sim \pi_1$
- $X_2 = 3 \qquad X_2 \sim \pi_2$

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 $X_0 \sim \pi_0$ $X_0 = 1$ $X_1 = 4$ $X_1 \sim \pi_1$ $X_2 = 3$ $X_2 \sim \pi_2$ $X_3 \sim \pi_3$ $X_3 = 4$ $X_4 = 2$ $X_4 \sim \pi_4$ $X_5 \sim \pi_5$ $X_5 = 3$ $X_6 \sim \pi_6$ $X_6 = 4$

Let's say we start at state I, i.e., $X_0 \sim \begin{bmatrix} 1 & 2 & 3 & 4 \\ 0 & 0 & 0 \end{bmatrix} = \pi_0$



Let's say we start at state I, i.e., $X_0 \sim \begin{bmatrix} 1 & 2 & 3 & 4 \\ 0 & 0 & 0 \end{bmatrix} = \pi_0$



- $\Pr[X_1 = 2 | X_0 = 1] = \frac{1}{2}$
- $\Pr[X_1 = 3 | X_0 = 1] = 0$
- $\Pr[X_1 = 4 | X_0 = 1] = \frac{1}{2}$
- $\Pr[X_1 = 1 | X_0 = 1] = 0$
- $t \quad \Pr[X_t = 2 | X_{t-1} = 4] = \frac{1}{4}$
- $\forall t \quad \Pr[X_t = 3 | X_{t-1} = 2] = 1$





Transition Matrix

A Markov Chain with **n** states can be characterized by the **n** x **n** transition matrix K :

$$\forall i, j \in \{1, 2, \dots, n\}$$
 $K[i, j] = \Pr[X_t = j \mid X_{t-1} = i]$

 $= \Pr[i \to j \text{ in one step}]$

<u>Note</u>: rows of K sum to I.

Some Fundamental and Natural Questions

What is the probability of being in state *i* after *t* steps (given some initial state)?

 $\pi_t[i] = ?$

What is the expected time of reaching state *i* when starting at state *j* ?

What is the expected time of having visited every state (given some initial state)?

•

How do you answer such questions?

Suppose we start at state | and let the system evolve.

How can we mathematically represent the evolution?



$$\begin{bmatrix} 1 & 2 & 3 & 4 \\ 0 & \frac{1}{2} & 0 & \frac{1}{2} \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & \frac{1}{4} & \frac{3}{4} & 0 \end{bmatrix}$$

Poll



3 4 2 Given $\pi_1 = \begin{bmatrix} 0 & \frac{1}{2} & 0 & \frac{1}{2} \end{bmatrix}$, what is π_2 ? $\frac{1}{4}$ $\frac{3}{4}$ 0 $\begin{bmatrix} 0 & \frac{1}{2} & \frac{1}{2} & 0 \end{bmatrix}$ $\left[0 \right]$ $\frac{5}{8}$ $\frac{3}{8}$ $\frac{1}{2}$ 0 $\frac{1}{2}$ $\left[0 \right]$ $\left[0 \right]$ 0 $\frac{1}{8}$ $\frac{7}{8}$ $\left[0 \right]$ $1 \quad 0$ |0| $\left[0 \right]$ 0





The probability of states after 1 step:

$$\begin{bmatrix} 1 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} 0 & \frac{1}{2} & 0 & \frac{1}{2} \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & \frac{1}{4} & \frac{3}{4} & 0 \end{bmatrix} = \begin{bmatrix} 0 & \frac{1}{2} & 0 & \frac{1}{2} \end{bmatrix}$$
$$\pi_{1}$$
the new state (probabilistic)



The probability of states after 2 steps:

$$\begin{bmatrix} 0 & \frac{1}{2} & 0 & \frac{1}{2} \end{bmatrix} \begin{bmatrix} 0 & \frac{1}{2} & 0 & \frac{1}{2} \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & \frac{1}{4} & \frac{3}{4} & 0 \end{bmatrix} = \begin{bmatrix} 0 & \frac{1}{8} & \frac{7}{8} & 0 \end{bmatrix}$$
$$\begin{array}{c} \pi_{2} \\ \pi_{2} \\ \text{the new state} \\ \text{(probabilistic)} \end{array}$$



$$\pi_1 = \pi_0 \cdot K$$
$$\pi_2 = \pi_1 \cdot K$$
So
$$\pi_2 = (\pi_0 \cdot K) \cdot$$

 $= \pi_0 \cdot K^2$

K

In general:

If the initial probabilistic state is $\begin{bmatrix} p_1 & p_2 & \cdots & p_n \end{bmatrix} = \pi_0$

$$p_i = probability$$
 of being in state *i*,

 $p_1 + p_2 + \cdots + p_n = 1$,

after t steps, the probabilistic state is:

$$\begin{bmatrix} p_1 & p_2 & \cdots & p_n \end{bmatrix} \begin{bmatrix} \text{Transition} \\ \text{Matrix} \end{bmatrix}^t = \pi_t$$

What happens in the long run?

i.e., can we say anything about π_t for large t ?

Suppose the Markov chain is "aperiodic".

Then, as the system evolves, the probabilistic state <u>converges</u> to a limiting probabilistic state.

As
$$t \to \infty$$
, for any $\pi_0 = \begin{bmatrix} p_1 & p_2 & \cdots & p_n \end{bmatrix}$:
 $\begin{bmatrix} p_1 & p_2 & \cdots & p_n \end{bmatrix}$ $\begin{bmatrix} Transition \\ Matrix \end{bmatrix}$ $\xrightarrow{t} \pi$

In other words:

Note:





Stationary distribution is $\begin{bmatrix} \frac{5}{6} & \frac{1}{6} \end{bmatrix}$.

$$\begin{bmatrix} \frac{5}{6} & \frac{1}{6} \end{bmatrix} \begin{bmatrix} 0.9 & 0.1 \\ 0.5 & 0.5 \end{bmatrix} = \begin{bmatrix} \frac{5}{6} & \frac{1}{6} \end{bmatrix}$$

In the long run, it is sunny 5/6 of the time, it is rainy 1/6 of the time.

How did I find the stationary distribution?

$$\begin{bmatrix} 0.9 & 0.1 \\ 0.5 & 0.5 \end{bmatrix}^2 = \begin{bmatrix} 0.86 & 0.14 \\ 0.7 & 0.3 \end{bmatrix}$$
$$\begin{bmatrix} 0.9 & 0.1 \\ 0.5 & 0.5 \end{bmatrix}^4 = \begin{bmatrix} 0.8376 & 0.1624 \\ 0.812 & 0.188 \end{bmatrix}$$
$$\begin{bmatrix} 0.9 & 0.1 \\ 0.5 & 0.5 \end{bmatrix}^8 = \begin{bmatrix} 0.833443 & 0.166557 \\ 0.832787 & 0.167213 \end{bmatrix}$$

Exercise: Why do the rows converge to π ?

We needed the Markov chain to be "aperiodic". What is a "periodic" Markov chain?



 $\pi_0 = \begin{bmatrix} 1 & 0 \end{bmatrix}$ $\pi_1 = \begin{bmatrix} 0 & 1 \end{bmatrix}$ $\pi_2 = \begin{bmatrix} 1 & 0 \end{bmatrix}$ $\pi_3 = \begin{bmatrix} 0 & 1 \end{bmatrix}$ There is still a stationary distribution. $\pi = \begin{bmatrix} 1/2 & 1/2 \end{bmatrix}$ $\begin{bmatrix} 1/2 & 1/2 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} 1/2 & 1/2 \end{bmatrix}$

But it is not a *limiting* distribution.

Summary so far

Markov Chains can be characterized by the transition matrix K.

$$K[i, j] = \Pr[X_t = j \mid X_{t-1} = i]$$
$$= \Pr[i \to j \text{ in one step}]$$

What is the probability of being in state *i* after *t* steps?

$$\pi_t = \pi_0 \cdot K^t \qquad \qquad \pi_t[i] = (\pi_0 \cdot K^t)[i]$$

There is a unique invariant distribution π : $\pi = \pi \cdot K$ For aperiodic Markov Chains: $\pi_t \to \pi$ as $t \to \infty$.

The plan

Motivating examples and applications

Basic mathematical representation and properties



How are Markov Chains applied ?

2 common types of applications:

I. Build a Markov chain as a statistical model of a real-world process.

Use the Markov chain to simulate the process.

e.g. text generation, music composition.

- 2. Use a measure associated with a Markov chain to approximate a quantity of interest.
 - e.g. Google PageRank, image segmentation

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Generate a superficially real-looking text given a sample document.

Idea:

From the sample document, create a Markov chain. Use a random walk on the Markov chain to generate text.

Example:

Collect speeches of Obama, create a Markov chain. Use a random walk to generate new speeches.

The Markov Chain:

- I. For each word in the document, create a node/state.
- 2. Put an edge word1 ---> word2 if there is a sentence in which word2 comes after word1.
- **3**. Edge probabilities reflect frequency of the pair of words.



"I jumped up. I don't know what's going on so I am coming down with a road to opportunity. I believe we can agree on or do about the major challenges facing our country."

Another use:

Build a Markov chain based on speeches of Obama. Build a Markov chain based on speeches of Bush.

Given a new quote, can predict if it is by Obama or Bush.

(by testing which Markov model the quote fits best)
Image Segmentation

Simple version

Given an image that contains an object, figure out: which pixels correspond to the object, which pixels correspond to the background.

i.e., label each pixel "object" or "background"

(user labels a small number of pixels with known labels)

Image Segmentation

The Markov Chain:

- I. Each pixel is a node/state.
- 2. There is an edge between adjacent pixels.
- 3. Edge probabilities reflect similarity between pixels.



Which one is more likely:

random walker first visits

"background" or

"object"?

Image Segmentation



PageRank is a measure of reputation:

The number and reputation of links pointing to you.

The Markov Chain:



PageRank is a measure of reputation: The number and reputation of links pointing to you.

The Markov Chain:

- I. Every webpage is a node/state.
- Each hyperlink is an edge:
 if webpage A has a link to webpage B, A ---> B
- **3a.** If A has *m* outgoing edges, each gets label 1/*m*.

3b. If **A** has no outgoing edges, put edge **A** ---> **B** \forall **B** (jump to a random page)

<u>A little tweak:</u>

Random surfer jumps to a random page with 15% prob.

Stationary distribution: probability of being in state A in the long run

PageRank of webpage A

=

The stationary probability of A



Google PageRank

Google:

"PageRank continues to be the heart of our software."

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