

15-251

# Great Theoretical Ideas in Computer Science

Introduction to Computational Complexity III:  
Space Complexity and Circuit Complexity

February 10th, 2015

# Today's Menu

Space complexity

Circuit complexity

# Space Complexity

How should we define space complexity?  
Should the input count?

# Definition

A TM has **space complexity**  $S(\cdot)$  if for every input  $x$ , it uses only  $S(|x|)$  cells of the tape.

For 1-tape TM,  $S(n) \geq n$  if the machine has to read the whole input.

So we actually consider a 2-tape TM:

- Tape 1 contains the input and is **read-only**
- Tape 2 is called the **work tape**, it is readable and writable.

The space complexity of the machine is defined with respect to the number of **work tape** cells it uses.

# Example

$$L = \{0^k 1^k : k \geq 0\}$$

On input string  $w$ :

- Scan the input and **reject** if a 0 is found to the right of a 1.
- Repeat while both 0s and 1s remain on the tape:
  - Scan the tape, cross off a single 0 and a single 1.
- If 0s remain but no 1s remain or  
1s remain but no 0s remain **reject**
- Else **accept**

(will need to copy the input to the work tape)

$O(n)$  space

# Example

$$L = \{0^k 1^k : k \geq 0\}$$

On input string  $w$ :

- Scan the input and **reject** if a 0 is found to the right of a 1.
- Scan the input and count the number of 0s and 1s.
- If the counts are not the same **reject**
- Else **accept**

$O(\log n)$  space

# Example

$$L = \{0^k 1^k : k \geq 0\}$$

```
def twoFingers(s):  
    lo = 0  
    hi = len(s)-1  
    while (lo < hi):  
        if (s[lo] != 0 or s[hi] != 1):  
            return False  
        lo += 1  
        hi -= 1  
    return True
```

$O(\log n)$  space



# What can a log-space machine do?

Keep a pointer to a constant number of positions in the input.

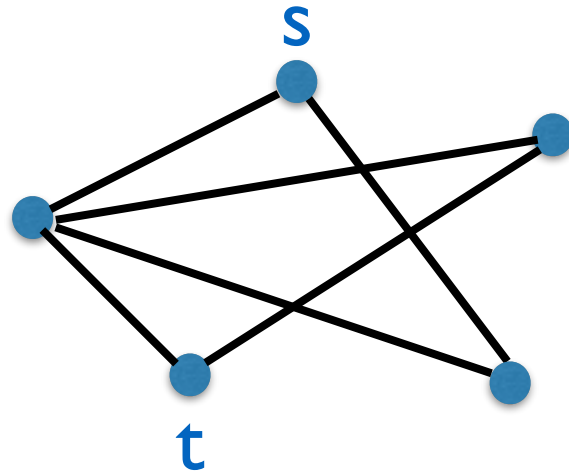
Count up to  $\text{poly}(n)$ .  $\log_2 n^k = k \log_2 n$

Keep logarithmic number of boolean variables.

# Reachability problem

Input: A set of “cities”, a set of “roads” between cities, and two specific cities **s** and **t**.

Output: **Yes** if we can reach **t** from **s**. **No** otherwise.



A “graph” with  
5 nodes/vertices  
and 6 edges.

(imagine there are millions of vertices)

**Omer Reingold (2004):**

This problem is decidable using  $O(\log n)$  space.

# Example

## Satisfiability (SAT)

Given a Boolean formula, is it satisfiable?

$$(x_1 \vee x_2) \wedge (x_3 \vee \neg x_2) \wedge \neg x_1$$

$$\exists x_1 \exists x_2 \dots \exists x_n \varphi(x_1, x_2, \dots, x_n)$$

## QSAT (TQBF)

Given a quantified Boolean formula, is it true?

$$Q_1 x_1 Q_2 x_2 \dots Q_n x_n \varphi(x_1, x_2, \dots, x_n)$$

(Each  $Q_i$  is  $\exists$  or  $\forall$ .  $\varphi$  is allowed to have constants.)

# Example

$$\Psi = Q_1 x_1 Q_2 x_2 \dots Q_n x_n \varphi(x_1, x_2, \dots, x_n)$$

QSAT can be decided using polynomial space.

size of  $\varphi$ :  $m$

size of input:  $O(n + m)$

Let  $\Psi|_{x_1=b}$  be  $\Psi$  with  $Q_1$  dropped,  
and all occurrences of  $x_1$  is replaced with  $b$ .

$A(\Psi)$  :

if  $n = 0$ : ... just do it  $O(m)$  space

if  $Q_1 = \exists$ : output  $(A(\Psi|_{x_1=0})$  or  $A(\Psi|_{x_1=1}))$

if  $Q_1 = \forall$ : output  $(A(\Psi|_{x_1=0})$  and  $A(\Psi|_{x_1=1}))$

# Example

$A(\Psi)$  :

if  $n = 0$ : ... just do it  $O(m)$  space

if  $Q_1 = \exists$ : output ( $A(\Psi|_{x_1=0})$  or  $A(\Psi|_{x_1=1})$ )

if  $Q_1 = \forall$ : output ( $A(\Psi|_{x_1=0})$  and  $A(\Psi|_{x_1=1})$ )

Let  $S(n, m)$  = space used by algorithm  $A$ .

**Observation:** recursive calls  $A(\Psi|_{x_1=0})$  and  $A(\Psi|_{x_1=1})$  can use the same space.

$$S(n, m) = S(n - 1, m) + O(n + m)$$

$$S(n, m) = O(n \cdot m + n^2)$$

(at most quadratic in the input length)

# Recall: time complexity classes

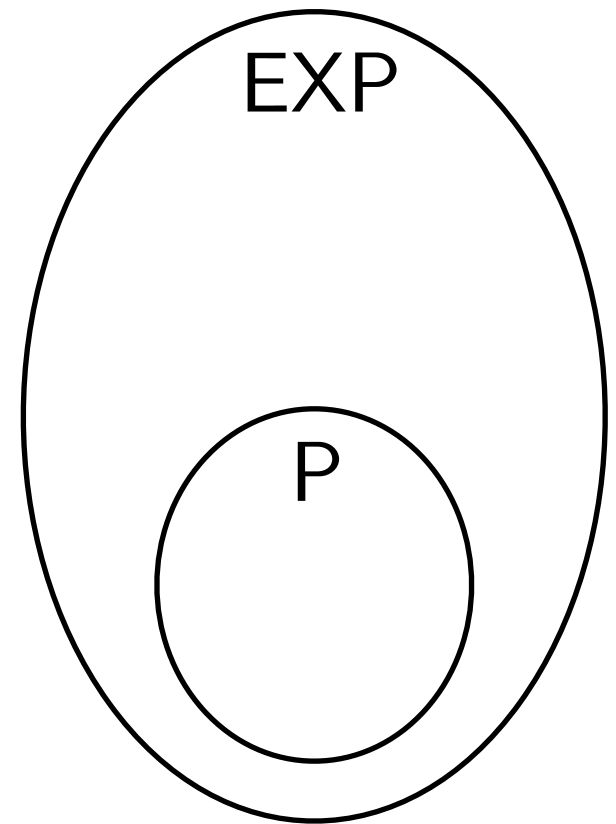
$\text{DTIME}(T(n)) = \{L : L \text{ is decided by an } O(T(n)) \text{ time algorithm.}\}$

$$P = \bigcup_{k \in \mathbb{N}} \text{DTIME}(n^k)$$

$$\text{EXP} = \bigcup_{k \in \mathbb{N}} \text{DTIME}(2^{n^k})$$

$$P \subsetneq \text{EXP}$$

(Time hierarchy theorem)



# Space complexity classes

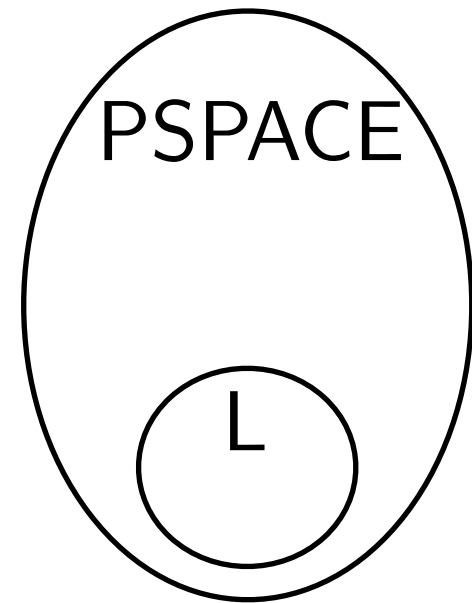
$\text{DSPACE}(S(n)) = \{L : L \text{ is decided by an } O(S(n)) \text{ space algorithm.}\}$

$$\text{PSPACE} = \bigcup_{k \in \mathbb{N}} \text{DSPACE}(n^k)$$

$$L = \text{DSPACE}(\log n)$$

$$L \subseteq \text{PSPACE}$$

$$L = \text{PSPACE} \text{ ???}$$



# Hierarchy Theorems

## Time Hierarchy Theorem:

Let  $T(n)$  be a time-constructible function, and  $\epsilon > 0$ .

Then there is a problem which cannot be decided in time  $T(n)$ , but can be decided in time  $T(n)^{1+\epsilon}$ .

$$\text{i.e., } \text{DTIME}(T(n)) \subsetneq \text{DTIME}(T(n)^{1+\epsilon})$$

## Space Hierarchy Theorem:

Let  $S(n)$  be a space-constructible function, and  $\epsilon > 0$ .

Then there is a problem which cannot be decided in space  $S(n)$ , but can be decided in space  $S(n)^{1+\epsilon}$ .

$$\text{i.e., } \text{DSPACE}(S(n)) \subsetneq \text{DSPACE}(S(n)^{1+\epsilon})$$



# Hierarchy Theorems

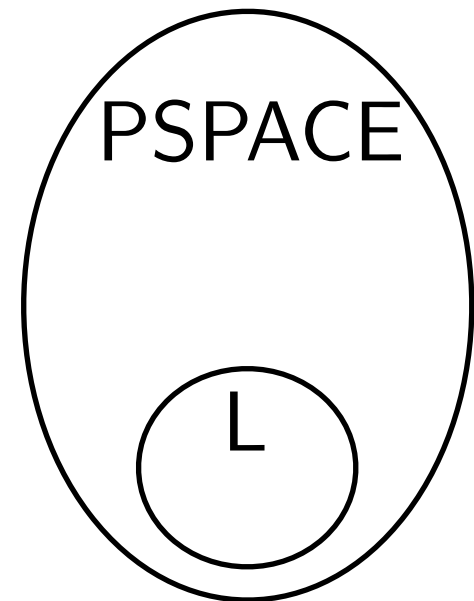
## Space Hierarchy Theorem:

Let  $S(n)$  be a space-constructible function, and  $\epsilon > 0$ .

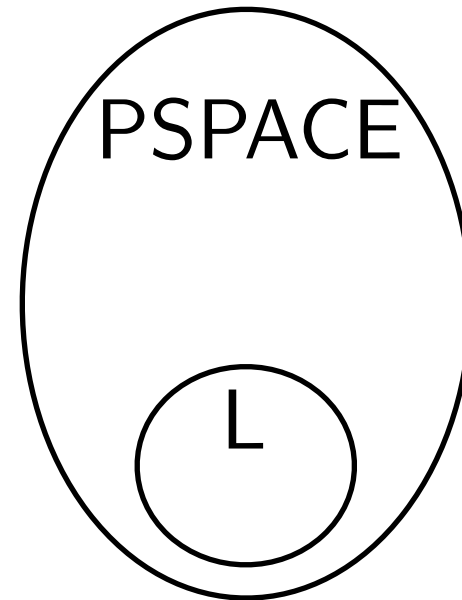
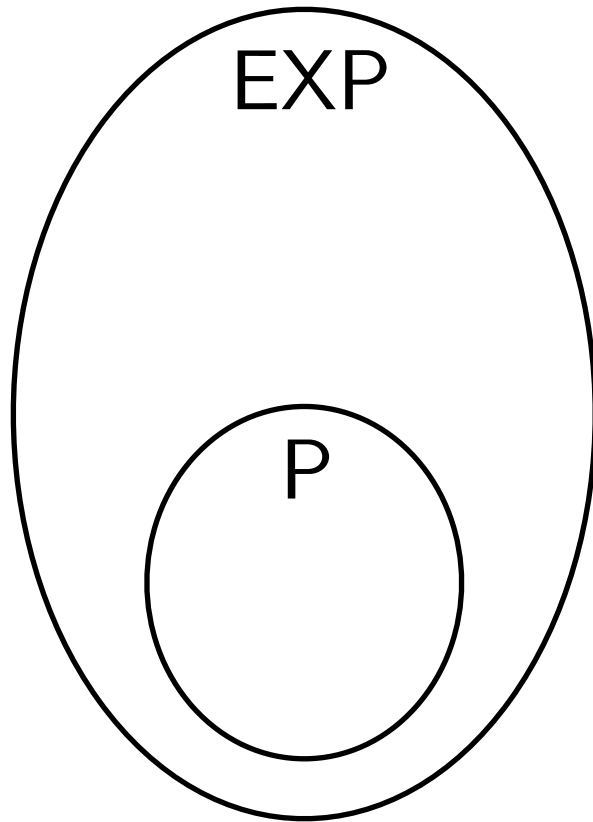
Then there is a problem which cannot be decided in space  $S(n)$ , but can be decided in space  $S(n)^{1+\epsilon}$ .

i.e.,  $\text{DSPACE}(S(n)) \subsetneq \text{DSPACE}(S(n)^{1+\epsilon})$

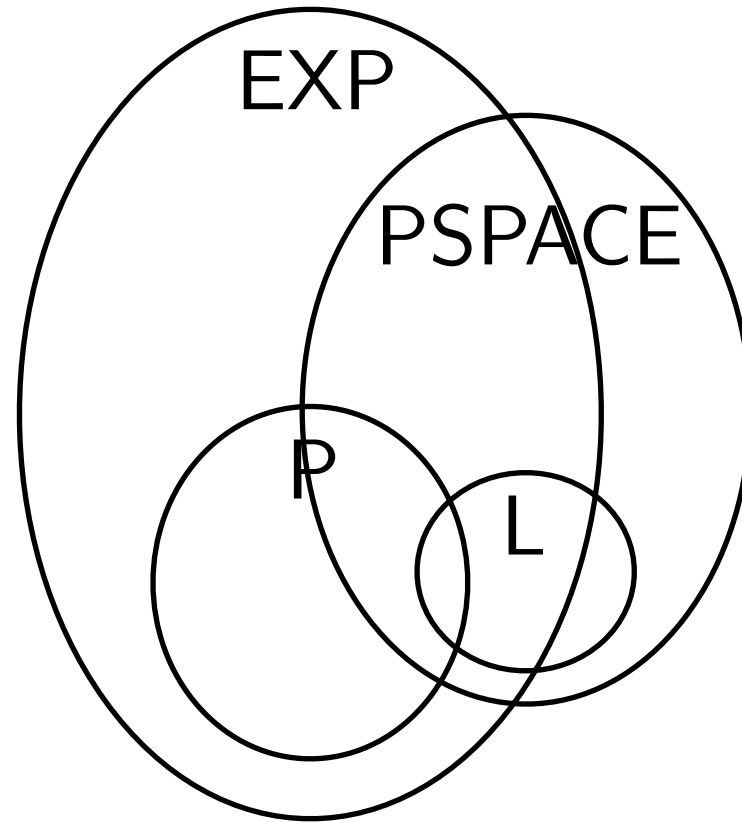
**Corollary:**  $L \subsetneq \text{PSPACE}$



# Relationship between space and time



# Relationship between space and time



**???**

# Relationship between space and time

## Theorem:

If a TM decides a language using  $S(\cdot)$  space, where  $S(n) \geq \log_2 n$ , then it decides the language using  $2^{O(S(n))}$  time.

## Proof:

Recall a configuration of a TM is a string

$$uqv \quad u, v \in \Gamma^*, \quad q \in Q$$

This is a snapshot of the TM's computation.

The information encoded in a configuration:

- current state
- the position of the tape head (work and input)
- contents of the tape (work)

# Relationship between space and time

## Proof (continued):

The information encoded in a configuration:

- current state
- the position of the tape head (work and input)
- contents of the tape (work)

If the TM takes  $t$  steps on a certain input, there is a sequence of configurations:  $c_1, c_2, \dots, c_t$

**Observation 1:**  $c_i \neq c_j$ , for  $i \neq j$

(otherwise the TM would be in an infinite loop.)

**Observation 2:**  $t \leq \#$  possible configurations

# Relationship between space and time

## Proof (continued):

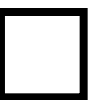
Observation 1:  $c_i \neq c_j$ , for  $i \neq j$

Observation 2:  $t \leq \#$  possible configurations

Number of possible configurations is:

$$\begin{aligned} & |Q| \cdot n \cdot S(n) \cdot |\Gamma|^{S(n)} \\ &= C \cdot 2^{\log_2 n} \cdot 2^{\log_2 S(n)} \cdot 2^{(\log_2 |\Gamma|)S(n)} \\ &= C \cdot 2^{\log_2 n + \log_2 S(n) + O(S(n))} \\ &= 2^{O(S(n))} \end{aligned}$$

So:  $t \leq 2^{O(S(n))}$



# Relationship between space and time

## Theorem:

If a TM decides a language using  $S(\cdot)$  space,  
where  $S(n) \geq \log_2 n$ ,  
then it decides the language using  $2^{O(S(n))}$  time.

**Corollary 1:**  $L \subseteq P$       (  $2^{c \log_2 n} = n^c$  )

**Corollary 2:**  $PSPACE \subseteq EXP$

# Relationship between space and time

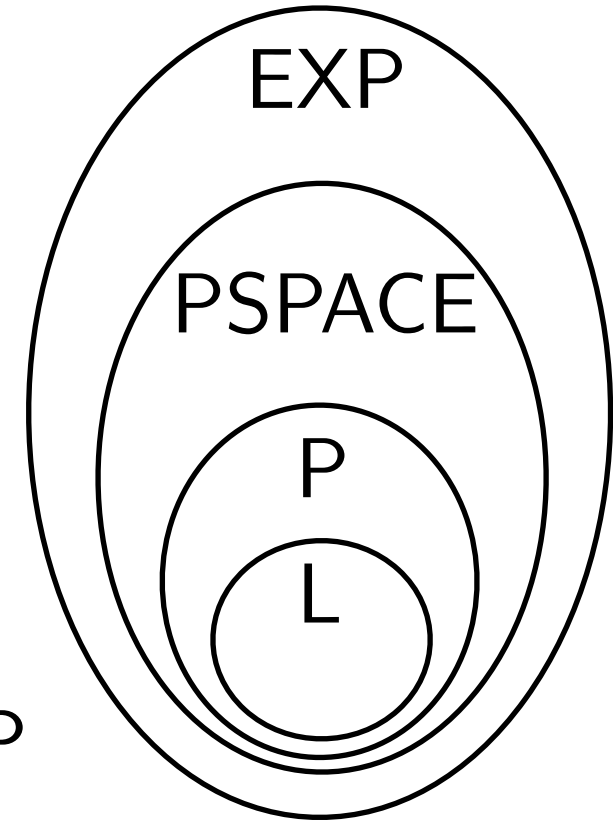
$$L \subseteq P \subseteq PSPACE \subseteq EXP$$

$$L \subsetneq PSPACE \implies$$

$$L \subsetneq P \quad \text{or} \quad P \subsetneq PSPACE$$

$$P \subsetneq EXP \implies$$

$$P \subsetneq PSPACE \quad \text{or} \quad PSPACE \subsetneq EXP$$



e.g., to show  $P \subsetneq PSPACE$ , you need a language  $A$  :

$$A \in PSPACE \quad \text{but} \quad A \notin P$$

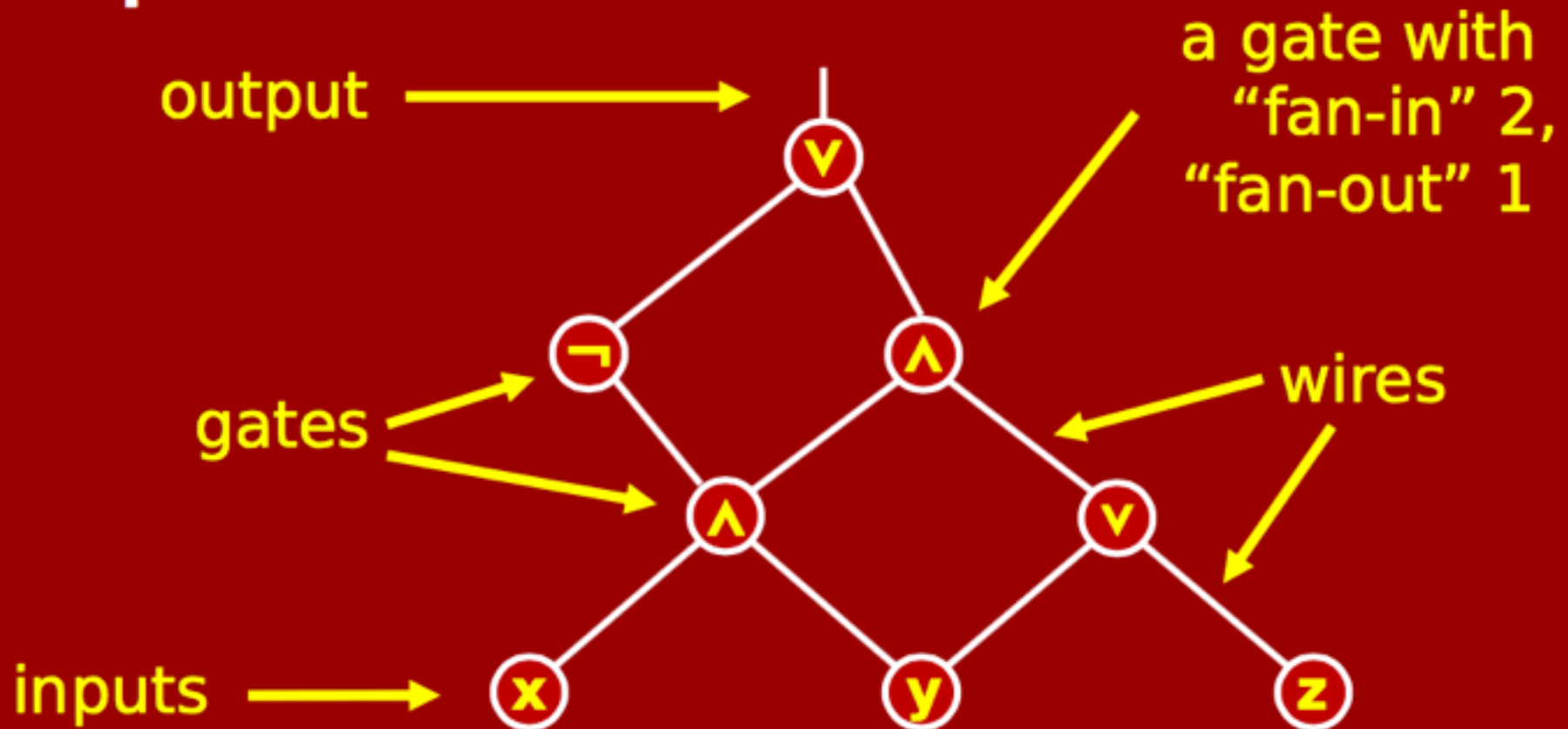


# Circuit Complexity

# Recall the definition

$((x \wedge y) \wedge (y \vee z)) \vee \neg(x \wedge y)$  is a formula.

**Depiction of the deduction:**



Such a picture is called a Boolean **circuit**.

# Recall the definition

A collection of **gates** and **inputs** connected by **wires**.

3 types of gates:

- binary AND gate
- binary OR gate
- unary NOT gate

Computes a function  $f : \{0, 1\}^n \rightarrow \{0, 1\}$

(or decides a language  $L_n \subseteq \{0, 1\}^n$ )

**Important:** A circuit can't handle all input lengths.  
Need a circuit for each input length.

# Circuit family

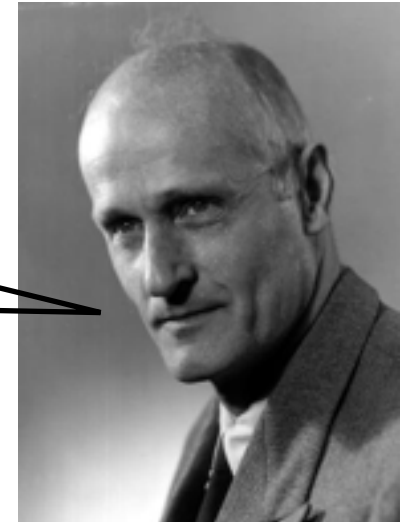
A **circuit family**  $C$  is a collection of circuits  $(C_0, C_1, C_2, \dots)$  where each  $C_n$  takes  $n$  input variables.

Let  $L_n \subseteq \{0, 1\}^n$  be the language decided by  $C_n$ .

Then  $L = \bigcup_{n \in \mathbb{N}} L_n$  is the language decided by  $C$ .

# Circuits vs TMs

An algorithm is a finite answer to infinite number of questions.



Stephen Kleene

A decider TM computes a function  $f : \{0, 1\}^* \rightarrow \{0, 1\}$

A TM is has a constant size description.

# Circuits vs TMs

A circuit family is an infinite answer to infinite number of questions.



Anil Ada

Perhaps not a very realistic model of computation.  
(it is a “non-uniform” model)

Every function is computable!

It is still a very useful model to study!

# Circuit size

The **size** of a circuit is the total number of gates (counting the input variables as gates too) in the circuit.

The **size** of a circuit family  $C$  is a function  $s(\cdot)$  such that  $s(n)$  is the size of  $C_n$ .

The **circuit complexity** of a language is the size of the minimal circuit family that decides the language.

(intrinsic complexity with respect to circuit size)

$L \in \text{SIZE}(s(n))$  if there is a circuit family of size  $O(s(n))$  that decides  $L$ .

# Maximum circuit size for a function

## Theorem:

For every language  $A$ ,  $A \in \text{SIZE}(2^n)$ .

## Proof:

Let  $f_A : \{0, 1\}^n \rightarrow \{0, 1\}$  correspond to  $A$ .

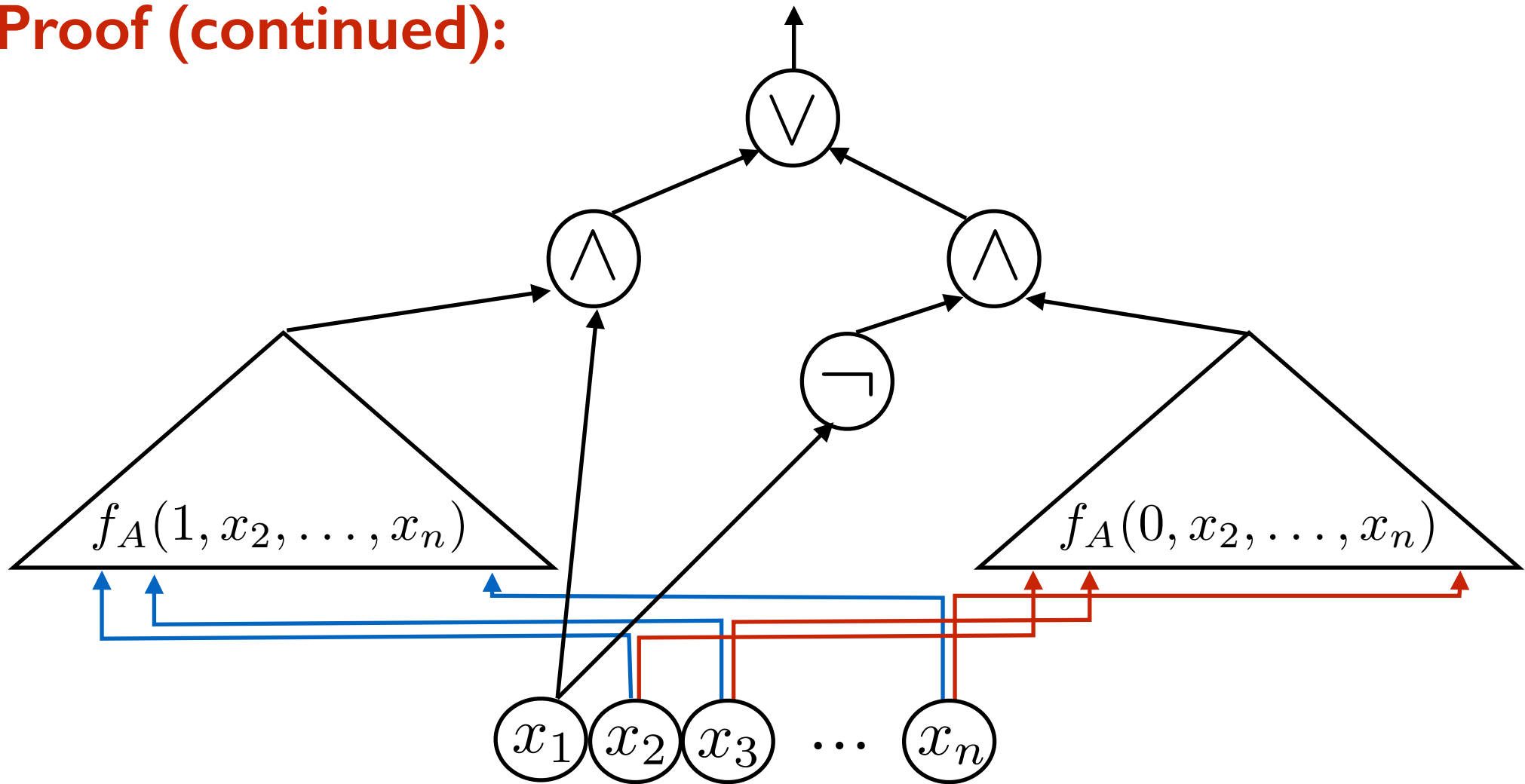
## Observation:

$$f_A(x_1, x_2, \dots, x_n) = (x_1 \wedge f_A(1, x_2, \dots, x_n)) \vee (\neg x_1 \wedge f_A(0, x_2, \dots, x_n))$$



# Maximum size for a function

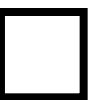
Proof (continued):



$$s(n) \leq 2s(n-1) + 5$$

$$s(1) \leq 3$$

$$\implies s(n) = O(2^n)$$



# Functions with exponential complexity

## Theorem:

There is a language  $L$  whose circuit complexity is at least  $2^n/4n$ .

## Proof:

Want to show: there is a function  $f : \{0, 1\}^n \rightarrow \{0, 1\}$  that cannot be computed by a circuit of size  $< 2^n/4n$ .

Observation: # possible functions is  $2^{2^n}$

Claim 1: # circuits of size  $s$  is  $\leq 2^{4s \log s}$

Claim 2: For  $s \leq 2^n/4n$ ,  $2^{4s \log s} < 2^{2^n}$

Then what we wanted to show follows immediately.

# Functions with exponential complexity

## Proof (continued):

Claim 1: # circuits of size  $s$  is  $\leq 2^{4s \log s}$

Claim 2: For  $s \leq 2^n / 4n$ ,  $2^{4s \log s} < 2^{2^n}$

Claim 2 is easy to verify. Proof of Claim 1:

For each circuit of size  $s$ ,  
we create a binary string of length  $\leq 4s \log s$

This mapping will be injective, so Claim 1 will follow.

Number the gates: 1, 2, 3, 4, ...,  $s$

For each gate in the circuit, write down:

- type of the gate (2 bits)
- from which gates the inputs are coming from

( $2 \log s$  bits)

Total:  $s(2 + 2 \log s)$  bits



# Remarks

That was due to Claude Shannon (1949).

Father of Information Theory.



Claude Shannon  
(1916-2001)

A **non-constructive** argument.

In fact, it is easy to show that **most** functions require exponential size circuits.

# Circuit complexity vs time complexity

## Theorem:

If  $A \in \text{DTIME}(T(n))$ , then  $A \in \text{SIZE}(T(n)^2)$ .

i.e.  $\text{DTIME}(T(n)) \subseteq \text{SIZE}(T(n)^2)$

## Corollary:

If  $A$  cannot be computed by polynomial size circuits, then  $A \notin P$ .

So to show  $P \subsetneq \text{PSPACE}$ , find a language in  $\text{PSPACE}$  that cannot be computed by polynomial size circuits.

## Current state of affairs:

After 60 years of research,

best lower bound for an explicit function:  $5n - \text{peanuts}$

# Advantages of working with circuits

A clean, simple mathematical definition.

Easy to create a hierarchy of problems.

- can restrict the depth (constant,  $\log n$ ,  $\log^2 n$ , ...)
- can allow other gates when the depth is restricted.
- can study monotone circuits.

# **Summary of Introduction to Computational Complexity**

# Summary

Unlike computability, computational complexity depends on the computational model.

Definition of time complexity of an algorithm.

The CS way of comparing functions.

$O(\cdot)$ ,  $\Omega(\cdot)$ ,  $\Theta(\cdot)$

How you represent the input matters.

If the input is a number, imagine it has millions of digits.



# Summary

Algorithms can do tricky things!  
Always ask “Can we do better?”

Definition of the famous complexity class  $P$ .

Not all decidable problems can be efficiently decided.

# Summary

Space complexity.

$$L \subseteq P \subseteq PSPACE \subseteq EXP$$

Circuit complexity.

- A nice and clean computational model.
- Related to time complexity.

We don't know how to prove lower bounds...