15-251
Great Theoretical Ideas in Computer Science
NP and NP-completeness I

February 24th, 2015
1. Basic algorithmic techniques
e.g. greedy algorithms, divide and conquer,
dynamic programming, linear programming,
semi-definite programming, etc.

2. Basic data structures
e.g. queues, stacks, hash tables, binary search trees, etc.

3. Identifying and dealing with intractable problems
Toolbox of a computer scientist

1. Basic algorithmic techniques
e.g. greedy algorithms, divide and conquer,
dynamic programming, linear programming,
semi-definite programming, etc…

2. Basic data structures
e.g. queues, stacks, hash tables, binary search trees, etc…

3. Identifying and dealing with intractable problems
Some examples

The Knapsack Problem

Input:

- $n$ items:
  - value $v_i$ (non-negative)
  - weight $w_i$ (non-negative, integral)
- capacity $W$ (non-negative, integral)
- target value $t$ (non-negative)

Output:

Yes, if there is a subset $S \subseteq \{1, 2, \ldots, n\}$ such that

\[ \sum_{i \in S} v_i \geq t \quad \text{and} \quad \sum_{i \in S} w_i \leq W \]
The Traveling Salesman Problem (TSP)

Input:
A graph $G = (V, E)$, edge weights $w_e$ (non-negative, integral) and target $t$.

Output:
Yes, if there is a cycle of cost at most $t$ that visits every vertex exactly once.
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The Traveling Salesman Problem (TSP)

Input:
A graph $G = (V, E)$, edge weights $w_e$ (non-negative, integral)
and target $t$.

Output:
Yes, if there is a cycle of cost at most $t$ that visits every vertex exactly once.

In which order should you visit the cities so the total cost is less than $20,000$?
Some examples

Satisfiability Problem (SAT)

Input:
A Boolean propositional formula.

\[ (x_1 \land \neg x_2) \lor (\neg x_1 \land x_3) \lor (\neg x_2 \land \neg x_3) \]

e.g. \( (x_1 \land \neg x_2) \lor (\neg x_1 \land x_3) \lor (\neg x_2 \land \neg x_3) \)

Output:
Yes if there is an assignment to the variables that makes the formula True.
Some examples

Theorem Proving Problem

Input:
A FOL formula. A target length $t$.

Output:
Yes if there is a proof of the formula in
FOL deductive calculus of length at most $t$. 

Yes if there is a proof of the formula in
FOL deductive calculus of length at most $t$. 

3. Identifying and dealing with intractable problems

After decades of research, no one has been able to come up with an efficient solution for these problems.

It would be fantastic if we could directly prove that these problems cannot be solved in poly-time.
3. Identifying and dealing with intractable problems

After decades of research, no one has been able to come up with an efficient solution for these problems.

It would be fantastic if we could directly prove that these problems cannot be solved in poly-time.

But we are far from doing this.

And who knows, maybe these problems are in $P$.

So what can we do???
3. Identifying and dealing with intractable problems

So what can we do???

We can try to gather evidence that these problems are hard.

And in fact, we will be able to do this!

These problems are described as \textbf{NP-hard} or \textbf{NP-complete}. (synonyms for “\textit{computationally intractable}”)

You have to know what these mean!

In fact, every scientist and engineer should know what these mean!
Goal:

Find evidence that, say TSP, is computationally hard.
Revisiting reductions

A central concept used to compare the “difficulty” of problems.

will differ based on context

Now we are interested in polynomial time decidability vs not polynomial time decidability

Want to define: \( A \leq B \)

- \( B \) is at least as hard as \( A \)
- (with respect to polynomial time decidability).

\[
\begin{align*}
\text{If } B \text{ poly-time decidable} & \implies A \text{ poly-time decidable} \\
B \in P & \implies A \in P \\
A \text{ not poly-time decidable} & \implies B \text{ not poly-time decidable} \\
A \notin P & \implies B \notin P
\end{align*}
\]
Revisiting reductions

Definition:

\[ A \leq^P_T B \ ( A \text{ polynomial time reduces to } B): \]

if it is possible to decide \( A \) in polynomial time using an algorithm that decides \( B \) in polynomial time.

\[ \begin{array}{c}
x \\ y \\ B(y) \\ A(x)
\end{array} \]
Revisiting reductions

```python
def b(...):
    # some code that solves the problem B

def a(...):
    # some code that solves the problem A
    # that makes calls to function b when needed
```

If \( b \) efficient (poly time) implies \( a \) efficient, then we write

\[
A \leq_{PT} B
\]

When you want to show \( A \leq_{PT} B \), you need to come up with an efficient \( a \).
Revisiting reductions

A:
Given a graph and an integer $k$, does there exist at least $k$ pairs of vertices connected to each other?

B:
Given a graph and a pair of vertices $(s,t)$, is $s$ and $t$ connected?

A poly-time reduces to B
Revisiting reductions

A:
Given a sequence of integers, and a number k, is there an increasing subsequence of length at least k?

\[3, 1, 5, 2, 3, 6, 4, 8\]

B:
Given two sequences of integers, and a number k, is there a common subsequence of length at least k?

\[3, 1, 5, 2, 3, 6, 4, 8\]
\[1, 5, 7, 9, 2, 4, 1, 0, 2, 0, 3, 0, 4, 0, 8\]

A poly-time reduces to B
The two sides of reductions

1. Expand the landscape of tractable problems.

If \( A \leq^P_T B \) and \( B \) is tractable, then \( A \) is tractable.

\[
B \in P \implies A \in P
\]

Whenever you are given a new problem to solve:

- check if it is already a problem you know how to solve in disguise.

- check if it can be reduced to a problem you know how to solve.
The two sides of reductions

2. Expand the landscape of intractable problems.

If \( A \leq_{PT} B \) and \( A \) is intractable, then \( B \) is intractable.

\[
A \notin P \implies B \notin P
\]

But we are pretty lousy at showing a problem is intractable.

Maybe we can still make good use of this…
Suppose we want to gather evidence that $A \notin P$. If we can show $L \leq^P_T A$ for many $L$ (including some $L$ that we really think should not be in $P$) then that would be good evidence that $A \notin P$. 
Definitions of C-hard and C-complete

**Definition:**
Let $C$ be some set of decision problems. We say that decision problem $A$ is $C$-hard if

$$C \leq_P^T A \quad \text{for all } C \in C$$

$A$ is harder than every problem in $C$.

**Definition:**
We say that decision problem $A$ is $C$-complete if

- $A$ is $C$-hard
- $A \in C$

$A$ is the hardest problem in $C$. 
**Definitions of C-hard and C-complete**

**Definition:**

Let \( C \) be some set of decision problems. We say that decision problem \( A \) is \( C \)-hard if

\[
C \leq_T^P A
\]

for all \( C \in C \)

**Observations:**

Suppose \( A \) is \( C \)-hard.

- If there is a problem in \( C - P \), then \( A \notin P \).
- If \( A \in P \), every problem in \( C \) is in \( P \).
  
  (In a sense, \( A \) encodes all problems in \( C \).)
Recall the goal

**Goal**: Find evidence that, say TSP, is computationally hard.

If $A$ is $C$-hard for a really big set $C$, that is some evidence that $A$ is computationally hard.

The bigger the $C$, the better!

So what is a good choice for $C$ if we want to show TSP is $C$-hard?
Recall the goal

**Goal:** Find evidence that, say TSP, is computationally hard.

What if we let $\mathcal{C}$ be the set of all languages?

Can it be true that TSP is $\mathcal{C}$-hard?

What if we let $\mathcal{C}$ be the set of all languages decidable using Brute Force Search (BFS)?

Can it be true that TSP is $\mathcal{C}$-hard?
How can we identify the problems solvable using BFS? What would be a reasonable definition?

What is common about the Knapsack Problem, TSP, SAT, and Theorem Proving Problem?

Seems hard to find a solution. BUT, quite easy to verify a given solution.
A complexity class for BFS

Seems hard to find a solution.

BUT, quite easy to verify a given solution.

• Given a satisfying assignment to a SAT formula, can easily verify that it indeed satisfies the formula.

• Given a cycle that visits every vertex in a graph, can easily verify it is indeed a cycle that visits every vertex.

• Given a proof for a FOL sentence, can easily verify it is indeed a valid proof.

We often call the solution a “proof” for the fact that the instance is in the corresponding language.
A complexity class for BFS

Seems hard to find a solution.
BUT, quite easy to verify a given solution.

BFS goes through the solution space one by one to find a solution.

Easy to distinguish a needle from hay.
But the haystack is exponentially large.
Informally:

A decision problem is in $\text{NP}$ if:
whenever we have a Yes instance,
there is a simple proof for this fact.
Informally:

A decision problem is in \( \text{NP} \) if:
- whenever we have a \textbf{Yes} instance,
  there is a \textit{simple} proof for this fact.

1. The length of the \textit{proof} is polynomial in the input size.
2. The \textit{proof} can be verified/checked in polynomial time.
The complexity class NP

Formally:

**Definition:**

A language $A$ is in NP if

- there is a polynomial time TM $V$
- a polynomial $p$

such that for all $x$:

$$x \in A \iff \exists u \text{ with } |u| \leq p(|x|) \text{ s.t. } V(x, u) = 1$$

“$x \in A$ iff there is a polynomial length proof $u$ that is verifiable by a poly-time algorithm.”
The complexity class NP

Formally:

Definition:
A language $A$ is in NP if
- there is a polynomial time TM $V$
- a polynomial $p$

such that for all $x$:

$$x \in A \iff \exists u \text{ with } |u| \leq p(|x|) \text{ s.t. } V(x, u) = 1$$

If $x \in A$, there is some proof that leads $V$ to accept.
If $x \notin A$, every “proof” leads $V$ to reject.
The complexity class \textbf{NP}

“\( x \in A \) iff there is a polynomial length \textbf{proof} \( u \) that is verifiable by a poly-time algorithm.”

If \( x \in A \), there is some \textbf{proof} that leads \( V \) to \textbf{accept}.
If \( x \notin A \), every “\textbf{proof}” leads \( V \) to \textbf{reject}.

\textbf{SAT} \( \in \textbf{NP} \)

\( x \): a Boolean formula
\( u \): an assignment to the variables that makes \( x \) True.
The complexity class NP

“\( x \in A \) iff there is a polynomial length proof \( u \) that is verifiable by a poly-time algorithm.”

If \( x \in A \), there is some proof that leads \( V \) to accept.
If \( x \notin A \), every “proof” leads \( V \) to reject.

**TSP \( \in \text{NP} \)**

\( x \): a graph with edge weights, and a target \( t \)
\( u \): a cycle of cost at most \( t \)
that visits each vertex exactly once.

proof = certificate = solution
The complexity class NP

2 Observations:

1. Every decision problem in \( \text{NP} \) can be solved using BFS.
   - Go through all possible proofs \( u \), and run \( V(x, u) \)

2. This is a pretty BIG class!

Contains everything in \( \text{P} \).

- If \( A \in \text{P} \), it has a poly-time decider \( M \).

\( V \) takes as input:

- real input \( x \), and empty string as proof \( u \)

\( V \) just runs \( M(x) \) and returns its output.

People expect that \( \text{NP} \) contains much more than \( \text{P} \).
Coming back to our goal

A language in $\text{NP-c}$ represents the hardest language in $\text{NP}$.

In fact, if we believe $\text{P} \neq \text{NP}$,

$A \in \text{NP-c} \implies A \notin \text{P}$

We wanted to find evidence that the Knapsack problem, TSP, SAT, Theorem Proving problem are not in $\text{P}$.

Could it be true that one of them is $\text{NP}$-complete?

Is there any decision problem that is $\text{NP}$-complete?
Coming back to our goal

Is there any decision problem that is NP-complete?

If $A \in \text{NP-c}$, it is like $A$ encodes all problems whose solutions can be efficiently verifiable.

(If we could solve $A$ in poly-time, we could solve every problem in NP in poly-time.)

Is NP-completeness a useful definition?
The Cook-Levin Theorem

Theorem (Cook 1971 - Levin 1973):

SAT is NP-complete.

That is, every problem in NP polynomial time reduces to SAT.
Karp’s 21 NP-complete problems

1972: “Reducibility Among Combinatorial Problems”

- 0-1 Integer Programming
- Clique
- Set Packing
- Vertex Cover
- Set Covering
- Feedback Node Set
- Feedback Arc Set
- Directed Hamiltonian Cycle
- Undirected Hamiltonian Cycle
- 3SAT
- SAT-CNF
- Partition
- Clique Cover
- Exact Cover
- Hitting Set
- Knapsack
- Steiner Tree
- 3-Dimensional Matching
- Job Sequencing
- Max Cut
- Chromatic Number
Thousands of problems are known to be NP-complete. (including SAT, TSP, Knapsack, Theorem Proving)
Some other examples

Longest Common Subsequence
Given a set of sequences, and a number k, is there a subsequence of length at least k that is common to all the given sequences?

Subset Sum
Given a set of integers, and a separate integer k, is there a subset of the integers that sum to k?

Longest Path
Given a graph and an integer k, is there a path of length at least k?
Some other examples

Sudoku (arbitrary dimension)

Super Mario Bros
Given a Super Mario Bros level, is it completable?

Tetris
Given a sequence of Tetris pieces, and a number $k$, can you clear more than $k$ lines?
And many more…

Amazingly, all of these problems are “equivalent” to each other.

If $A$ and $B$ are NP-complete, then

$$A \leq_T B \quad \text{and} \quad B \leq_T A$$
You want to show $A$ is NP-complete.

i.e., $A$ is in NP, and for every $B \in \text{NP}$, $B \leq^P_T A$.

How can you do it?

Observation:

Suppose you know $L$ is NP-hard,

i.e., $B \leq^P_T L$ for every $B \in \text{NP}$.

If you can show $L \leq^P_T A$

then $A$ is NP-hard too!
You want to show $A$ is NP-complete.

3 Steps:

1. Show that $A$ is in NP.

2. Pick your favorite NP-complete problem $L$.

3. Show that $L \leq_{PT} A$.

i.e., given a poly-time algorithm for $A$, come up with a poly-time algorithm for $L$. 
How do you prove a problem is NP-complete?

Cool!

How did Cook-Levin show SAT is NP-complete???

Will have to wait for this…
If $A$ is NP-hard, 
that seems to be good evidence that $A \notin P$.

(if you believe $P \neq NP$)

But is $P \neq NP$??
The P vs NP Question
What does NP stand for anyway?

Not Polynomial?
None Polynomial?
No Polynomial?
Nurse Practitioner?

It stands for **Nondeterministic Polynomial time**.

Languages in NP are the languages solvable in polynomial time by a nondeterministic TM.

DFA $\leftrightarrow$ SFA (actually called NFA)

DTM $\leftrightarrow$ NTM
What does NP stand for anyway?

Other contenders for the name of the class:

- Herculean
- Formidable
- Hard-boiled
- PET

- “possibly exponential time”
- “provably exponential time”
- “previously exponential time”
The P vs NP question

Yes, if you solve it, you get 1 million dollars.

But this understates the importance of the problem!

We are now pretty confident that this is one of the deepest questions we have ever asked.
The two possible worlds

\[
\begin{align*}
\text{NP-hard} & \quad \text{NP-c} \\
\text{NP} & \quad \text{P}
\end{align*}
\]

\[
\begin{align*}
P = \text{NP} = \text{NP-c}
\end{align*}
\]
The P vs NP question

To show $P \neq NP$:

pick you favorite NP-complete problem, 
show that it cannot be solved in polynomial time.

To show $P = NP$:

pick you favorite NP-complete problem, 
show that it can be solved in polynomial time.

$P = NP$ is equivalent to $\text{SUDOKU} \in P$
## What do experts think?

### Two polls from 2002 and 2012

<table>
<thead>
<tr>
<th></th>
<th>P ≠ NP</th>
<th>P = NP</th>
<th>Ind</th>
<th>DC</th>
<th>DK</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>2002</strong></td>
<td>61 (61%)</td>
<td>9 (9%)</td>
<td>4 (4%)</td>
<td>1 (1%)</td>
<td>22 (22%)</td>
</tr>
<tr>
<td><strong>2012</strong></td>
<td>126 (83%)</td>
<td>12 (9%)</td>
<td>5 (3%)</td>
<td>5 (3%)</td>
<td>1 (0.6%)</td>
</tr>
</tbody>
</table>

Number of respondents in 2002: 100
Number of respondents in 2012: 152
What do experts think?

Common arguments you’ll hear:

If P = NP, someone would have found an efficient algorithm for an NP-complete problem.

Verifying a given solution is quite easy.

Coming up with a solution seems to require “creativity”.

Can creativity be automated?
What do experts think?

Common arguments you’ll hear:

Recall: \[ L \subseteq P \subseteq \text{PSPACE} \subseteq \text{EXP} \]

\[ L \subseteq P \subseteq \text{NP} \subseteq \text{PSPACE} \subseteq \text{EXP} \]

We know \[ L \neq \text{PSPACE} \]

We also know \[ P \neq \text{EXP} \]
How to deal with NP-complete problems?

1. Focus on tractable special cases
   e.g. Given some graph problem.
   Maybe it is easy for bipartite graphs, or trees.

2. Heuristics
   Algorithms that are not guaranteed to be always correct.

3. Try to do better than BFS

4. Approximation algorithms
Summary
How do you identify intractable problems? (problems not in $P$) e.g. SAT, TSP, …

Can’t prove they are intractable. Can we gather some sort of evidence?

Poly-time reductions. $A \leq^P_T B$

If we can show $L \leq^P_T A$, for many $L$, that can be good evidence that $A \not\in P$.

Definitions of $C$-hard, $C$-complete.

What is a good choice for $C$, if we want to show, say, SAT is $C$-hard?
Summary

- The complexity class NP
- NP-hard, NP-complete
- Cook-Levin Theorem: SAT is NP-complete
- Many natural problems are NP-complete
- So is that good evidence that a problem is intractable?
- The P vs NP question
How did Cook-Levin show SAT is NP-complete?

And examples of reductions that show other problems are NP-complete.